

Description

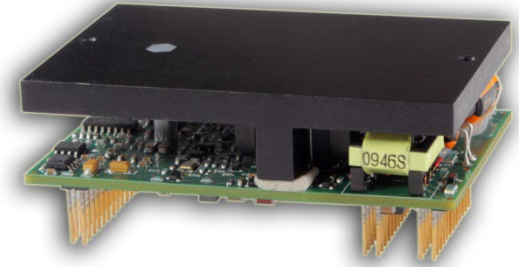
The DZXCANTE-040L080 digital servo drive is designed to drive brushed and brushless servomotors, stepper motors, and AC induction motors from a compact form factor ideal for embedded applications. This fully digital drive operates in torque, velocity, or position mode and employs Space Vector Modulation (SVM), which results in higher bus voltage utilization and reduced heat dissipation compared to traditional PWM. The drive can be configured for a variety of external command signals. Commands can also be configured using the drive's built-in Motion Engine, an internal motion controller used with distributed motion applications. In addition to motor control, this drive features dedicated and programmable digital and analog inputs and outputs to enhance interfacing with external controllers and devices.

The DZXCANTE-040L080 features a single RS232 interface used for drive configuration and setup. The CANopen interface can be used for online operation in networked applications. Drive commissioning is accomplished using DriveWare® 7, available for download at www.a-m-c.com. The DZX Hardware Installation Manual is available for download from www.a-m-c.com. All drive and motor parameters are stored in non-volatile memory.

The DZXCANTE-040L080 conforms to the following specifications and is designed to the Environmental Engineering Considerations as defined in MIL-STD-810F.

Extended Environment Performance

Ambient Temperature	-40°C to +75°C (-40°F to +167°F)
Storage Temperature	-50°C to +100°C (-58°F to +212°F)
Thermal Shock	-40°C to +75°C (-40°F to +167°F) in 2 min.
Relative Humidity	0 to 95% Non-Condensing
Vibration	30 Grms for 5 min. in 3 axes



Features

- ▲ Follows the CAN in Automation (CiA) 301 Communications Profile and 402 Device Profile
- ▲ Four Quadrant Regenerative Operation
- ▲ Space Vector Modulation (SVM) Technology
- ▲ Fully Digital State-of-the-art Design
- ▲ Programmable Gain Settings
- ▲ Fully Configurable Current, Voltage, Velocity and Position Limits
- ▲ PIDF Velocity Loop
- ▲ PID + FF Position Loop
- ▲ 12-bit Analog to Digital Hardware
- ▲ On-the-Fly Mode and Gain Set Switching

MODES OF OPERATION

- Profile Modes
- Cyclic Synchronous Modes
- Current
- Velocity
- Position
- Interpolated Position Mode (PVT)

COMMAND SOURCE

- ±10 V Analog
- PWM and Direction
- Encoder Following
- Over the Network
- Sequencing
- Indexing
- Jogging

FEEDBACK SUPPORTED

- ±10 VDC Position
- Halls
- Incremental Encoder
- Auxiliary Incremental Encoder
- Tachometer (±10 VDC)

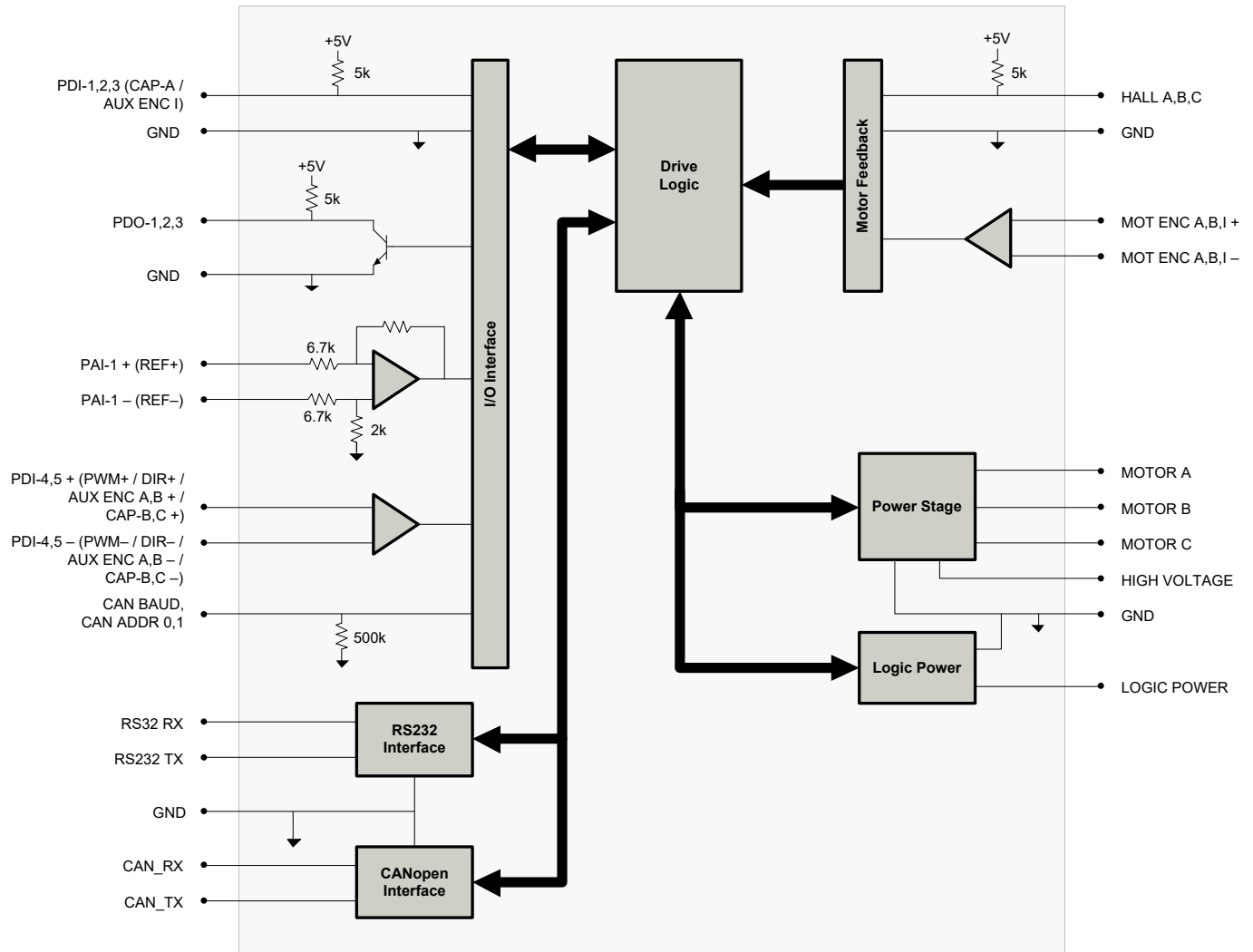
INPUTS/OUTPUTS

- 3 High Speed Captures
- 1 Programmable Analog Input (12-bit Resolution)
- 2 Programmable Digital Inputs (Differential)
- 3 Programmable Digital Inputs (Single-Ended)
- 3 Programmable Digital Outputs (Single-Ended)




AGENCY APPROVALS & COMPLIANCE CONSIDERATIONS

- RoHS
- MIL-STD-810F (as stated)
- MIL-STD-1275D (optional)
- MIL-STD-461E (optional)
- MIL-STD-704F (optional)
- MIL-HDBK-217 (optional)
- UL
- cUL
- CE Class A (LVD)
- CE Class A (EMC)

BLOCK DIAGRAM



Information on Approvals and Compliances

MIL-STD-810F	Environmental Engineering Considerations and Laboratory Tests – (as stated)
MIL-STD-1275D	Characteristics of 28 Volt DC Electrical Systems in Military Vehicles – (optional)
MIL-STD-461E	Requirements for the Control of Electromagnetic Interference Characteristics of Subsystems and Equipment – (optional)
MIL-STD-704F	Aircraft Electric Power Characteristics – (optional)
MIL-HDBK-217	Reliability Prediction of Electronic Equipment (MTBF) – (optional)
	US and Canadian safety compliance with UL 508c, the industrial standard for power conversion electronics. UL registered under file number E140173. Note that machine components compliant with UL are considered UL registered as opposed to UL listed as would be the case for commercial products.
	Compliant with European EMC Directive 2014/30/EU on Electromagnetic Compatibility (specifically EN 61000-6-4:2007/A1:2011 for Emissions, Class A and EN 61000-6-2:2005 for Immunity, Performance Criteria A). LVD requirements of Directive 2014/35/EU (specifically, EN 60204-1:2006/A1:2009, a Low Voltage Directive to protect users from electrical shock).
	The RoHS Directive restricts the use of certain substances including lead, mercury, cadmium, hexavalent chromium and halogenated flame retardants PBB and PBDE in electronic equipment.

SPECIFICATIONS

		Power Specifications	
Description	Units	Value	
DC Supply Voltage Range	VDC	10 - 80	
DC Bus Over Voltage Limit	VDC	88	
DC Bus Under Voltage Limit	VDC	8	
Logic Supply Voltage	VDC	5 (+/- 5%)	
Maximum Peak Output Current ¹	A (Arms)	40 (28.3)	
Maximum Continuous Output Current ²	A (Arms)	20 (20)	
Maximum Continuous Output Power	W	1520	
Maximum Power Dissipation at Continuous Current	W	80	
Internal Bus Capacitance ³	µF	20	
Minimum Load Inductance (Line-To-Line) ⁴	µH	250 (at 80 V supply); 150 (at 48 V supply); 75 (at 24 V supply)	
Switching Frequency	kHz	20	
Maximum Output PWM Duty Cycle	%	92	
		Control Specifications	
Description	Units	Value	
Communication Interfaces	-	CANopen (RS-232 for configuration)	
Command Sources	-	±10 V Analog, Encoder Following, Over the Network, PWM and Direction, Sequencing, Indexing, Jogging	
Feedback Supported	-	±10 VDC Position, Auxiliary Incremental Encoder, Halls, Incremental Encoder, Tachometer (±10 VDC)	
Commutation Methods	-	Sinusoidal, Trapezoidal	
Modes of Operation	-	Profile Modes, Cyclic Synchronous Modes, Current, Velocity, Position, Interpolated Position Mode (PVT)	
Motors Supported ⁵	-	Three Phase (Brushless Servo), Single Phase (Brushed Servo, Voice Coil, Inductive Load), Stepper (2- or 3-Phase Closed Loop), AC Induction (Closed Loop Vector)	
Hardware Protection	-	40+ Configurable Functions, Over Current, Over Temperature (Drive & Motor), Over Voltage, Short Circuit (Phase-Phase & Phase-Ground), Under Voltage	
Programmable Digital Inputs/Outputs (PDIs/PDOs)	-	5/3	
Programmable Analog Inputs/Outputs (PAIs/PAOs)	-	1/0	
Primary I/O Logic Level	-	5V TTL	
Current Loop Sample Time	µs	50	
Velocity Loop Sample Time	µs	100	
Position Loop Sample Time	µs	100	
Maximum Encoder Frequency	MHz	20 (5 pre-quadrature)	
		Mechanical Specifications	
Description	Units	Value	
Agency Approvals	-	RoHS, MIL-STD-810F (as stated), MIL-STD-1275D (optional), MIL-STD-461E (optional), MIL-STD-704F (optional), MIL-HDBK-217 (optional), UL, cUL, CE Class A (LVD), CE Class A (EMC)	
Size (H x W x D)	mm (in)	76.2 x 50.8 x 22.9 (3.0 x 2.0 x 0.9)	
Weight	g (oz)	116.2 (4.1)	
Baseplate Operating Temperature Range ⁶	°C (°F)	-40 - 85 (-40 - 185)	
Ambient Temperature Range	°C (°F)	-40 - 75 (-40 - 167)	
Storage Temperature Range	°C (°F)	-50 - 100 (-58 - 212)	
Thermal Shock	°C (°F)	-40 - 75 (-40 - 167) in 2 minutes	
Vibration	Grms	30 for 5 minutes in 3 axes	
Relative Humidity	-	0 - 95% Non-Condensing	
Cooling System	-	Natural Convection	
Form Factor	-	PCB Mounted	
P1 Connector	-	30-pin, 2.54 mm spaced, dual-row header	
P2 Connector	-	24-pin, 2.54 mm spaced, dual-row header	
P3 Connector	-	24-pin, 2.54 mm spaced, dual-row header	

Notes

1. Capable of supplying drive rated peak current for 2 seconds with 10 second foldback to continuous value. Longer times are possible with lower current limits.
2. Continuous I_{Arms} value attainable when RMS Charge-Based Limiting is used.
3. It is recommended to connect a 100µF / 100V electrolytic capacitor between High Voltage and Power Ground.
4. Lower inductance is acceptable for bus voltages well below maximum. Use external inductance to meet requirements.
5. Maximum motor speed for stepper motors is 600 RPM. Consult the hardware installation manual for 2-phase stepper wiring configuration.
6. Additional cooling and/or heatsink may be required to achieve rated performance.

PIN FUNCTIONS

P1 - Signal Connector			
Pin	Name	Description / Notes	I/O
1	CAN ADDR 0	CAN Bus Address Selector	I
2	CAN ADDR 1		I
3	PAI-1 + (REF+)	Differential Programmable Analog Input or Reference Signal Input (12-bit Resolution)	I
4	PAI-1 - (REF-)		I
5	GND	Ground	GND
6	CAN BAUD	CAN bus bit rate selector.	I
7	PDO-1	Programmable Digital Output	O
8	PDO-2	Programmable Digital Output	O
9	PDO-3	Programmable Digital Output	O
10	PDI-1	Programmable Digital Input	I
11	PDI-2	Programmable Digital Input	I
12	PDI-3 (CAP-A / AUX ENC I)	Programmable Digital Input or High Speed Capture or Auxiliary Encoder Index	I
13	RS232 RX	Receive Line (RS-232)	I
14	CAN RX	CAN Receive Line (Requires External Transceiver)	I
15	RS232 TX	Transmit Line (RS-232)	O
16	CAN TX	CAN Transmit Line (Requires External Transceiver)	O
17	PDI-4 + (PWM+ / AUX ENC A+ / CAP-B+)	Programmable Digital Input or PWM or Auxiliary Encoder or High Speed Capture (For Single-Ended Signals see DZ HW Installation Manual)	I
18	PDI-4 - (PWM- / AUX ENC A- / CAP-B-)		I
19	PDI-5 + (DIR+ / AUX ENC B+ / CAP-C+)	Programmable Digital Input or Direction or Auxiliary Encoder or High Speed Capture (For Single-Ended Signals see DZ HW Installation Manual)	I
20	PDI-5 - (DIR- / AUX ENC B- / CAP-C-)		I
21	GND	Ground	GND
22	HALL A	Single-ended Commutation Sensor Input (For Differential Inputs See MC1XDZ02 Datasheet For Recommended Signal Conditioning)	I
23	HALL B		I
24	HALL C		I
25	MOT ENC I+	Differential Encoder Index Input (See MC1XDZ02 Datasheet For Recommended Signal Conditioning)	I
26	MOT ENC I-		I
27	MOT ENC A+	Differential Encoder A Channel Input (See MC1XDZ02 Datasheet For Recommended Signal Conditioning)	I
28	MOT ENC A-		I
29	MOT ENC B+	Differential Encoder B Channel Input (See MC1XDZ02 Datasheet For Recommended Signal Conditioning)	I
30	MOT ENC B-		I

P2 and P3 - Power Connector			
Pin	Name	Description / Notes	I/O
1a	LOGIC PWR	Logic Supply Input (P2 only; Reserved on P3). Turn on the external logic supply first before turning on the main power supply.	I
1b	RESERVED		-
2a	2b	GND	GND
3a	3b	GND	GND
4a	4b	DC Power Input. 3A Continuous Current Rating Per Pin. 100µF, 100V external capacitor recommended between High Voltage and Ground.	I
5a	5b		I
6a	6b	RESERVED	-
7a	7b	Motor Phase Outputs. Current output distributed equally across both P2 and P3 connectors – 8 pins per motor phase, 3A continuous current carrying capacity per pin.	O
8a	8b		O
9a	9b		O
10a	10b		O
11a	11b		O
12a	12b		O

Pin Details
CAN ADDR 0 (P1-1)

This pin, CAN ADDR 0, as well as CAN ADDR 1, are used for CAN bus addressing. To set the CAN node address of a drive, use the formula

$$CANAddress = \frac{7 * Addr0}{3} + 8 * \frac{7 * Addr1}{3},$$

where *CANAddress* is the desired node address and *Addr0* and *Addr1* represent the voltage that should be applied to pins CAN ADDR 0 and CAN ADDR 1, respectively. The values for *Addr0* and *Addr1* are always integer multiples of 3/7 V within the range 0-3 V. Examples of the voltages required to set certain node addresses are given in the table below. Note that setting a CAN address of 0 will utilize the address stored in non-volatile memory.

CAN ADDR 0 Value (V)	CAN ADDR 1 Value (V)	CAN ADDR Tolerance (V)	CAN Address (Node #)
0	0	±0.1	Address stored in non-volatile memory
3/7 (0.43)	0	±0.1	1
6/7 (0.86)	0	±0.1	2
9/7 (1.3)	0	±0.1	3
...	...	±0.1	...
18/7 (2.57)	21/7 (3.0)	±0.1	62
21/7 (3.0)	21/7 (3.0)	±0.1	63

CAN BAUD (P1-6)

The CAN bit rate is set by applying the appropriate voltage to the CAN BAUD pin as given in the table below. Note that higher bit rates are possible when using the value stored in NVM.

CAN BAUD Value (V)	CAN BAUD Tolerance (V)	CAN Bus Bit Rate (bits/s)
0	±0.388	Bit rate stored in non-volatile memory
1	±0.388	500k
2	±0.388	250k
3	±0.388	125k

MECHANICAL INFORMATION

P1 - Signal Connector

Connector Information		30-pin, 2.54 mm spaced, dual-row header
Mating Connector	Details	Samtec: SSM-115-L-DV (SMT); BCS-115-L-D-PE (Pass-through)
	Included with Drive	No

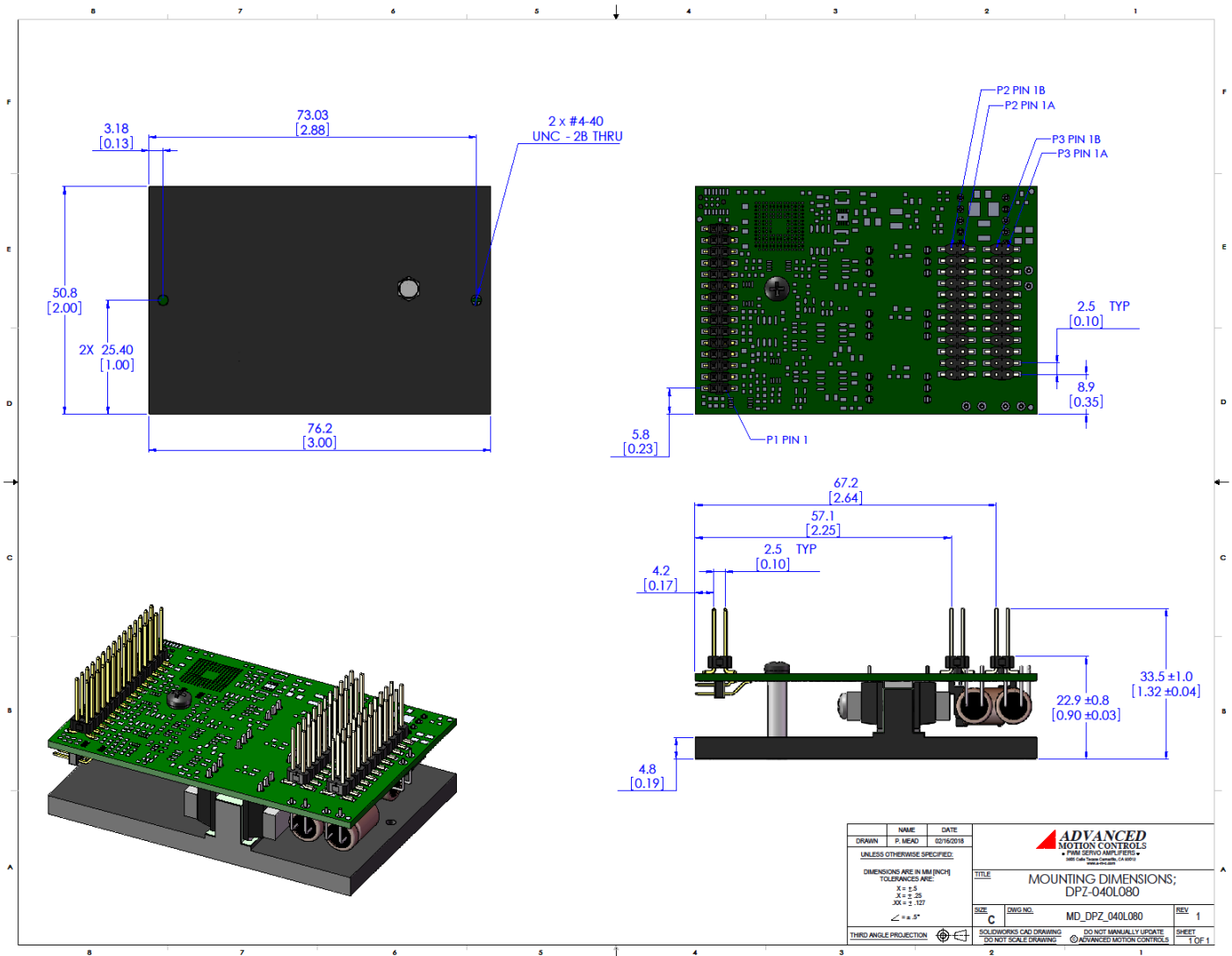
P2 - Power Connector

Connector Information		24-pin, 2.54 mm spaced, dual-row header
Mating Connector	Details	Samtec: SSM-112-L-DV (SMT); BCS-112-L-D-PE (Pass-through)
	Included with Drive	No

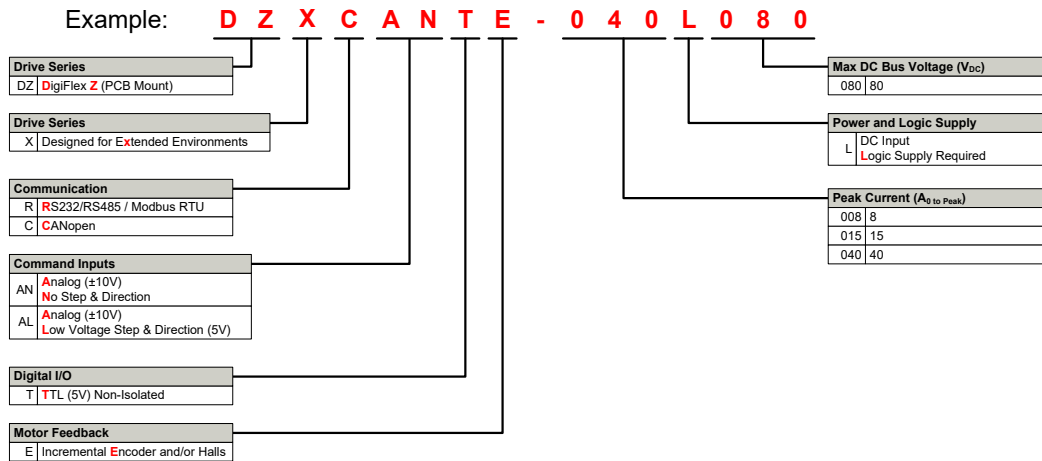
P3 - Power Connector

Connector Information		24-pin, 2.54 mm spaced, dual-row header
Mating Connector	Details	Samtec: SSM-112-L-DV (SMT); BCS-112-L-D-PE (Pass-through)
	Included with Drive	No

MOUNTING DIMENSIONS



PART NUMBERING INFORMATION



DigiFlex® Performance™ series of products are available in many configurations. All models listed in the selection tables of the website are readily available, standard product offerings.

ADVANCED Motion Controls also has the capability to promptly develop and deliver specified products for OEMs with volume requests. Our Applications and Engineering Departments will work closely with your design team through all stages of development in order to provide the best servo drive solution for your system. Equipped with on-site manufacturing for quick-turn customs capabilities, ADVANCED Motion Controls utilizes our years of engineering and manufacturing expertise to decrease your costs and time-to-market while increasing system quality and reliability.

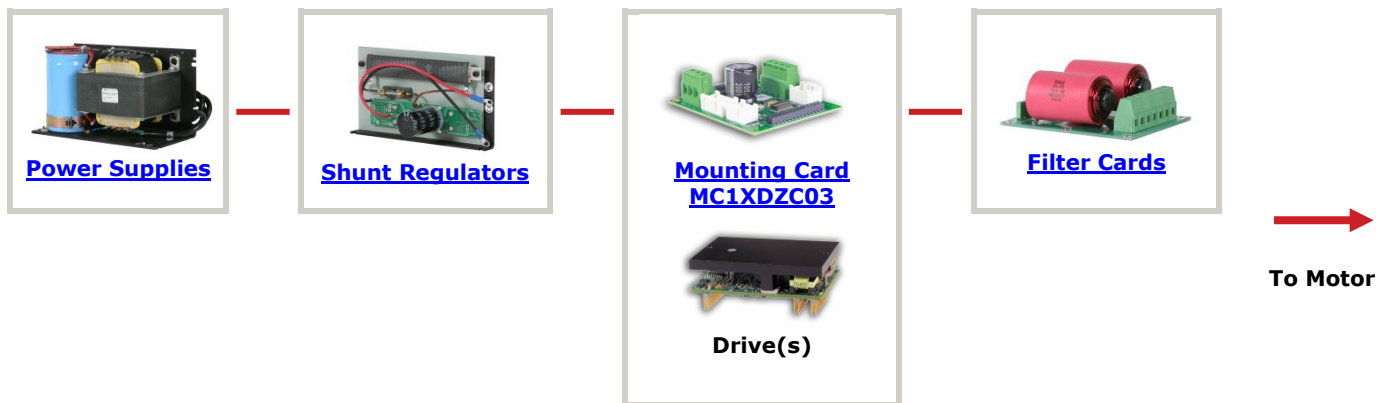
Examples of Customized Products

- ▲ Optimized Footprint
- ▲ Private Label Software
- ▲ OEM Specified Connectors
- ▲ No Outer Case
- ▲ Increased Current Resolution
- ▲ Increased Temperature Range
- ▲ Custom Control Interface
- ▲ Integrated System I/O
- ▲ Tailored Project File
- ▲ Silkscreen Branding
- ▲ Optimized Base Plate
- ▲ Increased Current Limits
- ▲ Increased Voltage Range
- ▲ Conformal Coating
- ▲ Multi-Axis Configurations
- ▲ Reduced Profile Size and Weight

Feel free to contact Applications Engineering for further information and details.

Available Accessories

ADVANCED Motion Controls offers a variety of accessories designed to facilitate drive integration into a servo system. Visit www.a-m-c.com to see which accessories will assist with your application design and implementation.



All specifications in this document are subject to change without written notice. Actual product may differ from pictures provided in this document.